

Modelling Traffic on Motorways:

State-of-the-Art,
Numerical Data Analysis,
and Dynamic Traffic Assignment

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Outline

- **Outline**
- **Part I: State-of-the-Art**
 - The Physics of Road Traffic and Transportation
 - Cellular Automata Models of Road Traffic
- **Part II: Numerical Analysis of Traffic Data**
 - Assessing Data Quality
 - Off-Line Travel Time Estimation
 - Tempo-Spatial Congestion Maps
- **Part III: Integrated Dynamic Traffic Assignment**
 - Combining Departure Time and Route Choice
 - Efficient Dynamic Network Loading
- **Conclusions and Perspectives**

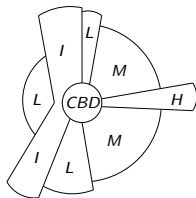
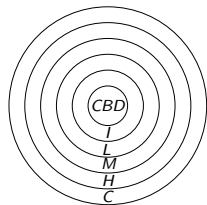
Part I

State-of-the-Art

Land-Use and Socio-Economic Behaviour

The demand for transportation is induced by people **wishing** to **participate** in **spatially separated** social, cultural, economic, ... **activities**.

⇒ Land-use models (Burgess 1925, Hoyt 1939, ...)

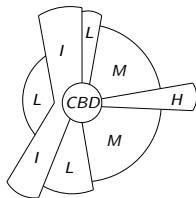
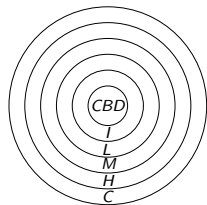


- CBD = central business district
- I = industry zone
- L/M/H = low-, middle-, and high-class residents
- C = commuter zone

Land-Use and Socio-Economic Behaviour

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⇒

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Geosimulation 2000
(sprawl)



Trip-Based Transportation Planning Models

Classical approach, e.g., the **four-step model** (4SM).
Travellers make certain decisions, thereby undertaking trips.

Trip generation

⇒ *How many trips ?* ⇒ **aggregation**

Trip distribution

⇒ *Where are they going ?* ⇒ **OD matrix**

Modal split

⇒ *What mode of transportation ?*

Traffic assignment

⇒ *Which routes ?*

Trip-Based Transportation Planning Models

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Modal split

Traffic assignment

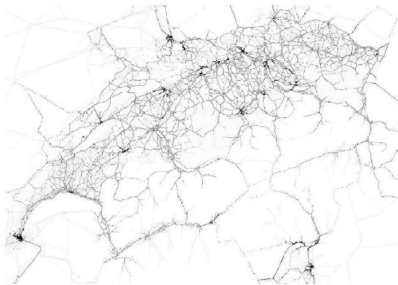
Route choice behaviour as dictated by
Wardrop's criteria:

User equilibrium \leftrightarrow System optimum

Activity-Based Transportation Planning Models

Basic units are not trips but **household activity patterns**.

- Generation of a **synthetic population**.
- Generation and scheduling of activity patterns \Rightarrow **agent plans**.
- Physical propagation of agents (plan execution).
 \Rightarrow **Day-to-day** and **within-day** dynamics lead to rescheduling.



Multi-agent simulation



"Switzerland at 08:00"

Macroscopic and Mesoscopic Traffic Flow Models

Describe how traffic propagates **physically** on a road.

Based on partial differential equations (high level of aggregation, low level of detail).

Macroscopic:

Fluid-dynamic models treat traffic as a compressible fluid (Navier-Stokes).

Mesoscopic:

Gas-kinetic models treat traffic as a many-particle system, deriving macroscopic equations from microscopic driver behaviour.

Microscopic and Submicroscopic Traffic Flow Models

Microscopic models explicitly consider interactions between vehicles in a traffic stream (low level of aggregation, high level of detail).

Car-following submodel

- Stimulus-response.
- Optimal velocity.
- Psycho-physiological spacing.
- Traffic cellular automata.
- Based on queueing theory.

Lane-changing submodel

- Modelling gap acceptance.
- Mandatory versus discretionary lane changes.

Submicroscopic models incorporate **physical characteristics** such as engine performance, gearbox operations, ... and **human decision taking processes**.

Historic Origins of Cellular Automata

Introduced in 1948 by **von Neumann** and **Ulam**; evolving in the 70s towards Conway's popular "*Game of Life*":

- Lattice \mathcal{L} .
- States Σ .
- Local neighbourhood \mathcal{N} .
- Local transition rule δ .

⇒

Global behaviour arises from local rule-based interactions.

In the 80s, **Wolfram** provided popularisation through an abundance of empirical experiments.

Cellular Automata Models of Road Traffic

Consider a **one-dimensional lattice** \mathcal{L} ($\Delta X = 7.5$ m, $\Delta T = 1$ s, $v_{\max} = 5$ cells/time step), corresponding to a single-lane traffic cellular automaton (TCA). Suppose the following rule set applies:

R1: acceleration and braking

$$v_i(t) \leftarrow \min\{v_i(t-1) + 1, g_{S_i}(t-1), v_{\max}\}$$

R2: randomisation

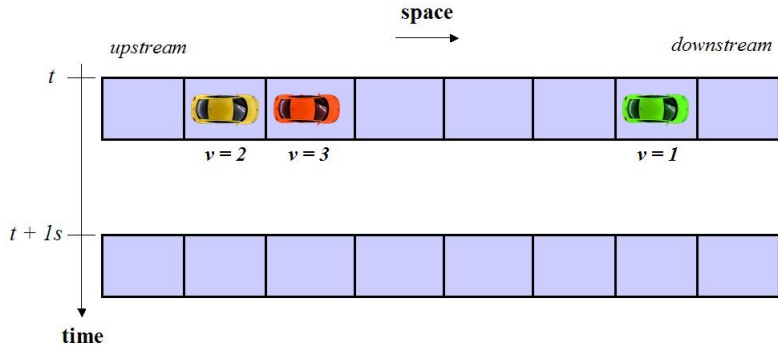
$$\xi(t) < p \Rightarrow v_i(t) \leftarrow \max\{0, v_i(t) - 1\}$$

R3: vehicle movement

$$x_i(t) \leftarrow x_i(t-1) + v_i(t)$$

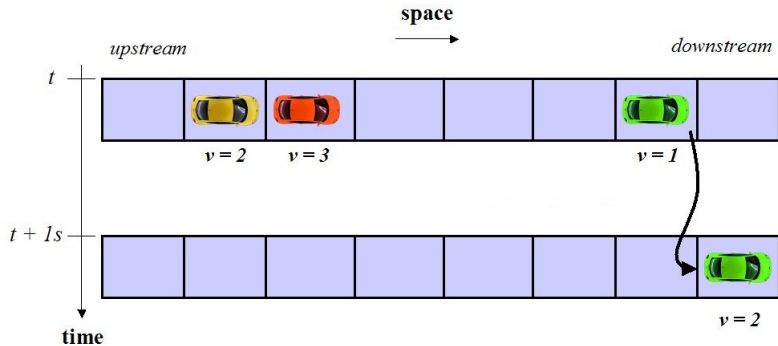
\Rightarrow Apply TCA rules to all vehicles **in parallel**.

Executing the Rule Set: An Illustrative Example



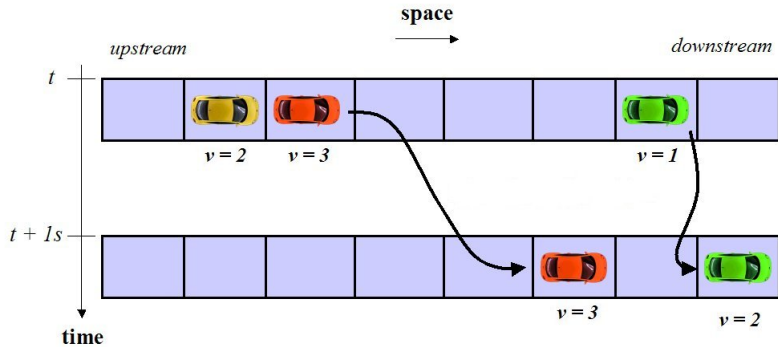
Set of local rules \Rightarrow car-following submodel

Executing the Rule Set: An Illustrative Example



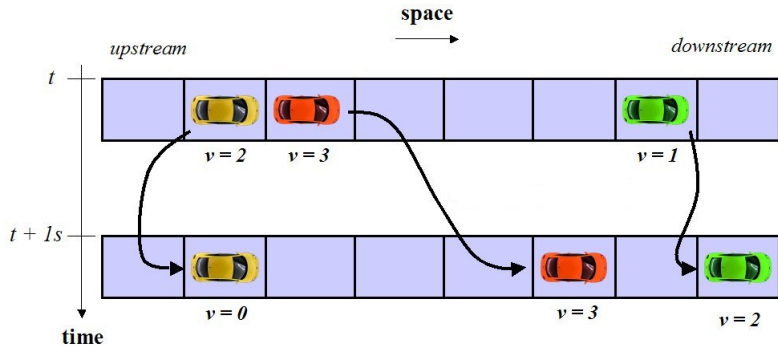
→ The green car can **accelerate** from 1 to 2 cells/time step.

Executing the Rule Set: An Illustrative Example



→ The red car **maintains** its speed.

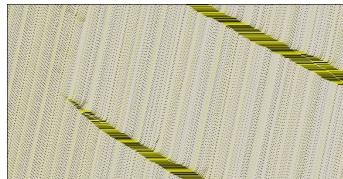
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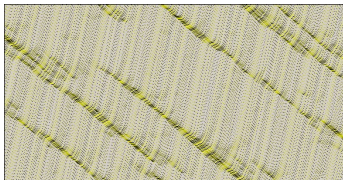
→ The yellow car must **brake** and stop to avoid a collision.

Some Flavours of Traffic Cellular Automata Models

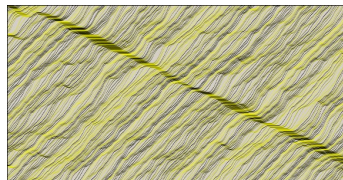
Velocity-dependent randomisation



Stochastic



With brake-lights



⇒ TCA+ Java™ Simulator (<http://smtca.dyns.cx>)

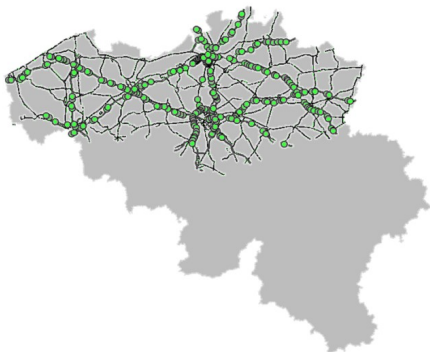
Part II

Numerical Analysis of Traffic Data

Collecting Traffic Flow Measurements

Consider Flanders' motorway road network:

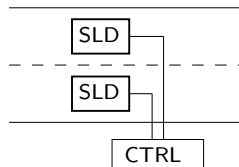
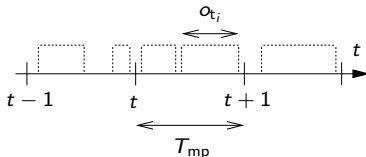
- Some 1600 loop detectors (with approximately 200 cameras).
- On for each lane, right before and after a complex.
- $\approx 10^6$ measurements/year ≈ 3.24 GB.



Single Inductive Loop Detectors

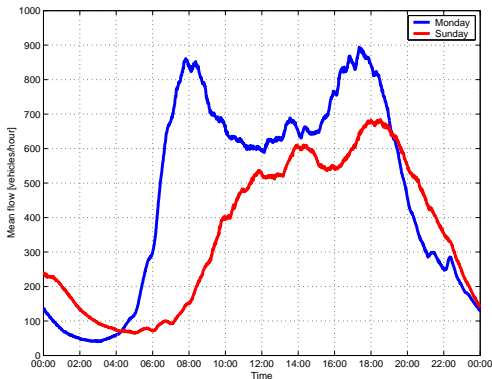
Each time a vehicle i passes over the detection zone, it is **counted** and its **on-time** o_{t_i} recorded. After a period T_{mp} of one minute, the following measurements are aggregated:

- Number of cars q_c (**internal classification !**).
- Number of trucks q_t (**internal classification !**).
- Occupancy ρ .
- Time-mean speed \bar{v}_t (**estimated !**).



Raw Traffic Flow Measurements

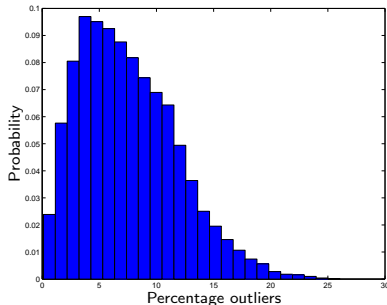
Consider the **average flows** on all Mondays and Sundays in 2003:



- ⇒ The Monday morning and evening peaks are clearly visible.
- ⇒ Sunday has an afternoon peak, increasing in intensity.

Statistical Outlier Detection

As opposed to structural failures of single inductive loop detectors, **occasional errors** occur as **outliers** in the data:



Summary statistics for 2003

Maximum	=	24.5 %
Mean	=	7.5 %
Std. dev.	=	4.4 %

- ⇒ Automatically detect and remove **statistical** outliers.
- ⇒ Fill in the missing values (e.g., reference days, multiple imputation, time series analysis, non-parametric models, ...).

Assessing Detector Malfunctioning

Based on the **Daily Statistics Algorithm** (DSA) of Chen et al. 2003.
For example, consider the following score for loop detector i :

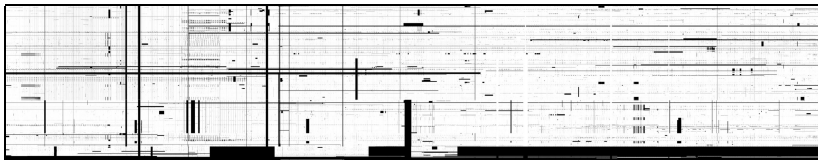
High occupancy samples

$$S_2(i, T_{\text{DSA}}) = \#\text{samples during } T_{\text{DSA}} \text{ with } \rho_i > \rho^*.$$

- For the year 2001, the database contained 1654 detectors.
- $T_{\text{DSA}} = 60$ minutes.
- $\rho^* = 35$ %.

⇒ Highly detailed detector maps
(e.g., 24 hours \times 365 days = 8760 pixels).

Illustrative Detector Maps



Horizontally: hour-of-year.

Vertically: detector ID.



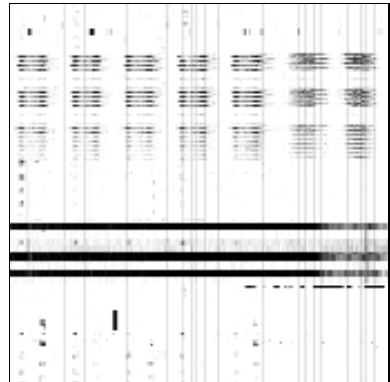
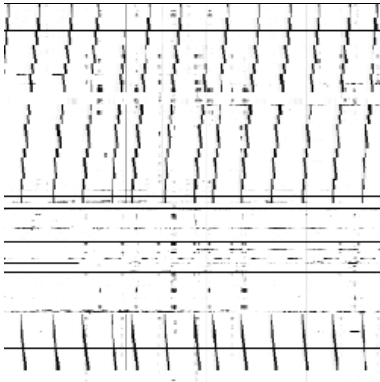
Dark horizontal lines: detector failure during a certain time period.

Dark vertical lines: failure of several neighbouring detectors.

Long vertical lines: archival failure at the central database.

Studying 2001 → 2005: **more failures at the central database.**

Illustrative Detector Maps

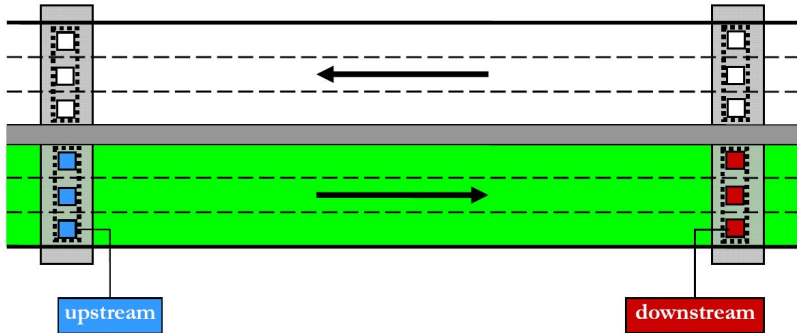


Slanted streaks: at successive detectors at successive time periods.

Short horizontal lines: high occupancies during day-time.

Travel Time Estimation: Problem Description

We are interested in the **computation** of travel times, based on **historical flow measurements***, obtained at both ends of a **motorway section** without on-/off ramps in between.



(*) For single inductive loop detectors, total vehicle counts are the most reliable.

Travel Time Estimation Algorithm

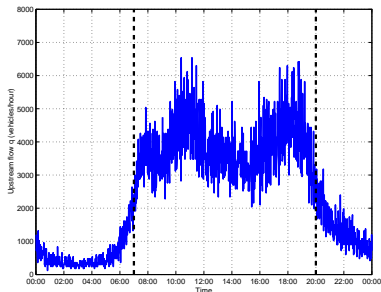
Assumptions

- There is conservation of the number of vehicles in the section.
- The *first-in, first-out* (FIFO) condition holds.

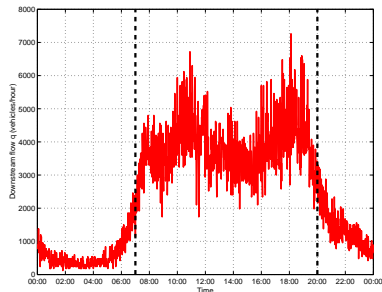
- (1) Aggregate flow measurements over all lanes.
- (2) Convert flow measurements into **cumulative counts**.
- (3) Synchronise upstream and downstream cumulative curves.
- (4) Correct for systematic errors between both posts.
- (5) Extract the distribution of the dynamic travel time.

An Example for Travel Time Estimation on the E40

Consider the E40 motorway between Erpe-Mere and Wetteren (three lanes), on Monday, April 4, 2003.



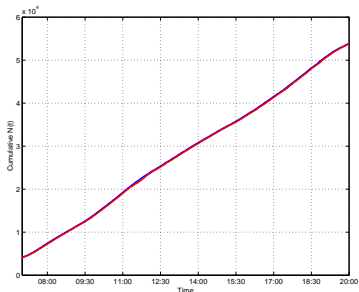
Upstream flows



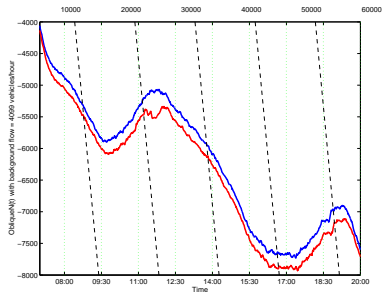
Downstream flows

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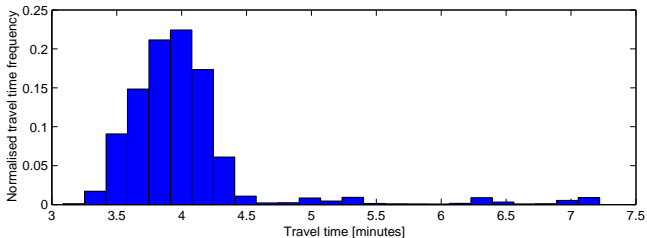
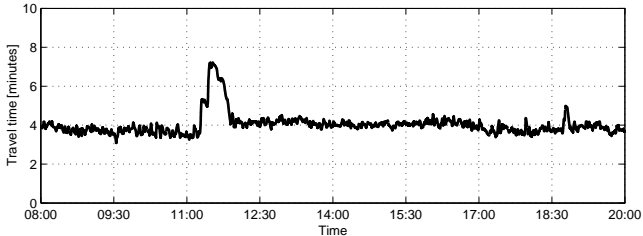
Cumulative curves



Oblique plot

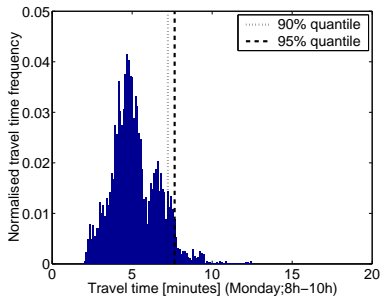
⇒ There is a **queue** growing at approximately 11:00.

Extracting the Distribution of the Dynamic Travel Time

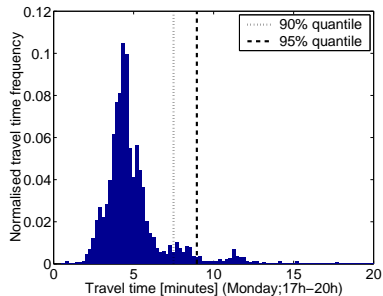


Assessing Travel Time Reliability

For a **typical Monday** in 2003, this becomes:



Median = 5.16 minutes
MAD = 0.43 minutes
90% = 7.23 minutes
95% = 7.66 minutes



Median = 4.97 minutes
MAD = 0.45 minutes
90% = 7.49 minutes
95% = 8.95 minutes

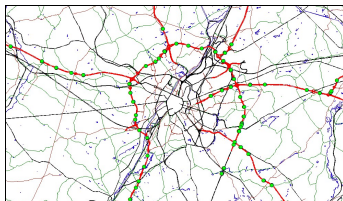
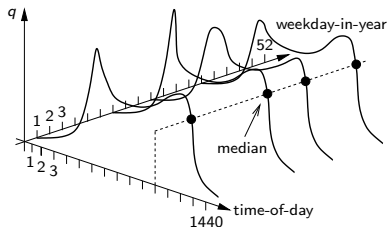
Constructing Tempo-Spatial Congestion Maps

For a given motorway, consider all measurements made on **similar weekdays**. Use the **mean speed** as an indicator for congestion.

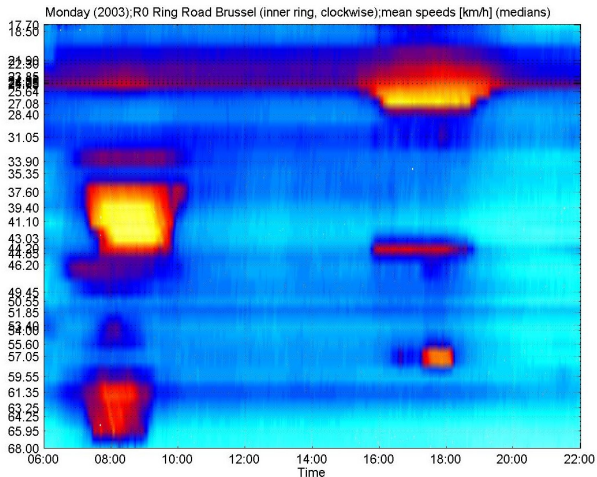
Robust estimators to eliminate outliers

The **median** (= 50% quantile) gives **structural** congestion.

The 95% quantile gives **incidental** congestion.



Structural Congestion on the R0 Ring Road

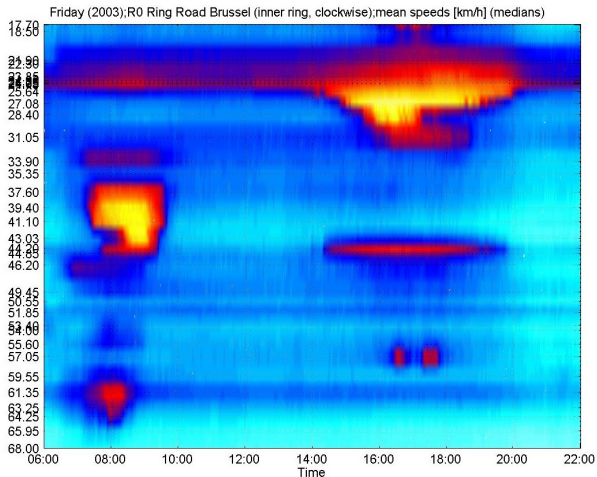


Monday

Severe **morning congestion** around Vilvoorde and Strombeek-Bever. Slower traffic at Machelen (E19) and Merchtem (E40).

Severe **evening congestion** around Vierarmenkruispunt, Tervuren, Wezembeek-Oppem.

Structural Congestion on the R0 Ring Road



Friday

Typically a **more pronounced evening congestion**, as opposed to a **milder morning congestion**.

Longer evening rush hour, especially near Vierarmenkruispunt and Strombeek-Bever.

Part III

Integrated Dynamic Traffic Assignment

Approaches to Dynamic Traffic Assignment

It is important to capture the **temporal** character of congestion (i.e., its buildup and dissolution). Travel times depend on the history of the system, implying **dynamic** traffic assignment (DTA):

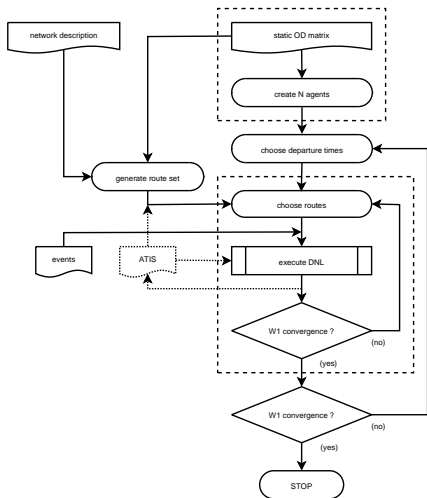
- Analytical versus **simulation-based** DTA.
- Deterministic versus **stochastic** DTA.
- The **integration** encompasses the following components:
 - Departure time choice (DTC).
 - Dynamic route choice (DRC).
 - Dynamic network loading (DNL).

⇒ Incorporate a given synthetic population.

⇒ Assume heterogeneous **unimodal** traffic, using an **efficient** DNL.

⇒ (DTC + DRC) + DNL ⇒ **equilibrium**.

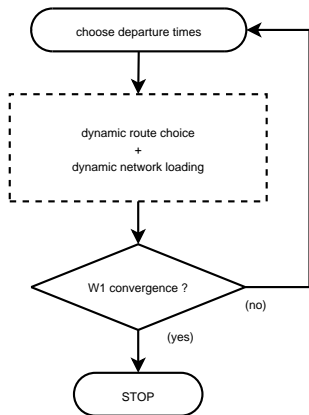
Overview of the Proposed Framework



⇒ Sequential DTC + DRC

- (1) Disaggregate static OD matrix into N agents.
- (2) Generate set of feasible routes.
- (3) Execute **departure time choice** (DTC) model.
- (4) Execute **dynamic route choice** (DRC) model.
- (5) Execute **dynamic network loading** (DNL) model.
- (6) Check convergence.

Departure Time Choice



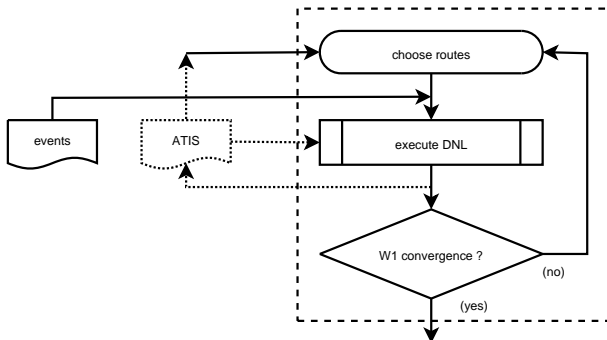
Check convergence using an agent's **generalised travel cost**:

$$C_{\text{total}_i}(t_{\text{departure}_i}) = C_{\mu_i}(\mu_i(t_{\text{departure}_i})) + C_{T_i}(T_i(t_{\text{departure}_i})) + \max\{C_{\beta_i}(t_{\text{PAT}_i} - (t_{\text{departure}_i} + T_i(t_{\text{departure}_i}))), 0\} + \max\{C_{\gamma_i}(t_{\text{departure}_i} + T_i(t_{\text{departure}_i}) - t_{\text{PAT}_i}), 0\}.$$

⇒ Take **schedule delay costs** into account.

Dynamic Route Choice

Assuming **known departure times**, all agents now select a route from the set of feasible routes between their origins and destinations.



An Efficient Dynamic Network Loading Model

We adopt a **microscopic** simulation approach.

BUT: Car-following and lane-changing submodels typically entail a high-computational burden.

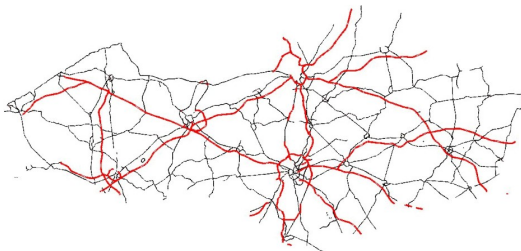


Consider a **traffic cellular automaton** as the underlying DNL model:

- Site oriented versus particle oriented \Rightarrow **hybrid** approach.
- Flexible architecture with respect to the choice of TCA model.
- Slowdown probabilities et cetera are properties of the links.
- JavaTM: performant and *“write once, run anywhere”*.

Tackling Large Scale Aspects

Even when using an efficient microscopic model like a traffic cellular automaton, **large-scale** scenarios provide a true challenge.



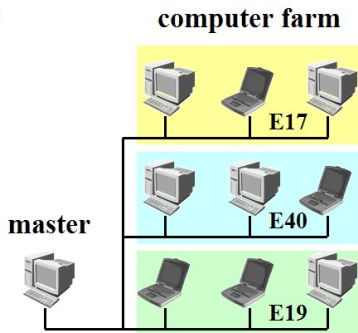
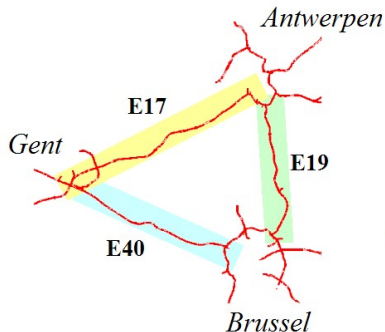
⇒ Flanders has ≈ 1300 km of highway roads.

⇒ This corresponds to $\approx 520,000$ cells (7.5 m/cell; 3 lanes/road).

Solution: divide the workload over different workers.

Parallelism Through Distributed Computing

- ⇒ We assume deployment in a **heterogeneous** environment (mixing grid-based and high-performance computing).
Assign all motorways to separate computing units:



Part IV

Summary and Perspectives

Summary and Contributions

- With respect to the state-of-the-art, we have provided:
 - A **logical and consistent terminology and notation** to tackle the existing a 'zoo of notations' ([Chapter 2](#)).
 - An **extensive overview** for traffic flow theory, transportation planning, and traffic flow modelling ([Chapters 2 and 3](#)).
 - A **complete survey and classification** of traffic cellular automata models from the behavioural point of view ([Chapter 4](#)).
- Considering traffic flow measurements, we have provided ([Chapter 6](#)):
 - A method to **track statistical outliers**.
 - A **visual technique** for quick assessments of structural and incidental detector malfunctioning.
 - A methodology for **deriving travel times** based on raw cumulative counts.
- Sequentially combining departure time choice and dynamic route choice, we **propose a framework** for dynamic traffic assignment, based on an efficient dynamic network loading model ([Chapter 7](#)).

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Future Research

- Considering the state-of-the-art:
 - A **consequent analysis** of the developed traffic flow models (mathematical properties, physical soundness, strengths and weaknesses).
 - The humanities and social sciences should consider the **psychological aspects** of human beings (e.g., self-organisation of the transportation system).
- **Mining data** stemming from detectors, GSM/GPS probe vehicles, ... to extract relevant and up-to-date traffic information (interaction between competitive producers and consumers).
- Construct a **practical implementation** of the proposed framework (considering calibration and validation issues, and the existence of an equilibrium).

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